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Solution Manual Digital Signal Processing 1.1 Suppose the input to an amplifier is $x_a(t) = \sin(2\pi f_0 t)$ and the steady-state output is $y_a(t) = 100 \sin(2\pi f_0 t + \phi_1) - 2 \sin(4\pi f_0 t + \phi_2) + \cos(6\pi f_0 t + \phi_3)$ (a) Is the amplifier a

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1.1 Suppose the input to an amplifier is $x_a(t) = \sin(2\pi f_0 t)$ and the steady-state output is $y_a(t) = 100 \sin(2\pi f_0 t + \phi_1) - 2 \sin(4\pi f_0 t + \phi_2) + \cos(6\pi f_0 t + \phi_3)$ (a) Is the amplifier a linear system or is it a nonlinear system? (b) What is

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1. First fold $x(n)$ and then delay the resulting signal by four samples. 2. First delay $x(n)$ by four samples. (c) Sketch the signal $x(-n + 4)$. (d) Compare the results in parts (b) and (c) and derive a rule for obtaining the signal $x(-n + k)$ from $x(n)$.

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