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### Discrete Time Control Systems Solution Manual

Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller ( $\mu P$ ), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + –  $r(t)$   $e(t)$  ADC  $\mu P$  DAC  $u(t)$  Plant ? ?  $y(t)$  4

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In stead, the operator expression for a discrete-time system, and the system's impulse response are representations two  $r$  for the same system; they are the coordinates of a point as seen from two different coordinate systems. Then a transformation of a system has an active meaning: for example, composing two systems to build a new system.

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